# Supplementary Material: Visual Domain Adaptation with Manifold Embedded Distribution Adaptation\*

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### Update

We notice that there are a huge number of deep transfer learning methods appear with new state-of-the-art results. Hence, we add this section to keep track of the latest results. We add the results on *Office-31*, *Office-Home, and Image-CLEF DA datasets*.

From the results, we can see that MEDA **significantly** outperforms all existing deep adversarial methods on Office-Home dataset (by 4.2%). On Office-31 and Image-CLEF DA datasets, the improvement is marginal. However, note that MEDA only needs ResNet to perform finetune on the source domaind data. Then, the finetuned model can easily extract features for the source and target domain. Compared to other methods that need to train the whole model with several extra hyperparameters to tune, MEDA is significantly improving the baseline results..

1. Office-31 dataset

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	Method	$A \rightarrow D$	$A \rightarrow W$	$D \rightarrow A$	$D \rightarrow W$	$W \rightarrow A$	$W \rightarrow D$	Average
cvpr16	ResNet-50	68.4	96.7	99.3	68.9	62.5	60.7	76.1
icml15	DAN [9]	80.5	97.1	99.6	78.6	63.6	62.8	80.4
nips16	RTN [11]	84.5	96.8	99.4	77.5	66.2	64.8	81.6
icml15	DANN [5]	82.0	96.9	99.1	79.7	68.2	67.4	82.2
cvpr17	ADDA [19]	86.2	96.2	98.4	77.8	69.5	68.9	82.9
icml17	JAN [12]	85.4	97.4	99.8	84.7	68.6	70.0	84.3
cvpr17	GTA [16]	89.5	97.9	99.8	87.7	72.8	71.4	86.5
aaai18	MADA [14]	90.1	97.4	99.6	87.8	70.3	66.4	85.2
cvpr18	CAN [21]	81.5	63.4	85.5	65.9	99.7	98.2	82.4
aaai19	JDDA [3]	82.6	95.2	99.7	79.8	57.4	66.7	80.2
ACMMM18	Our MEDA	86.2	85.9	72.3	97.4	73.4	99.4	85.8

Table 1: Classification accuracy (%) on Office-31 dataset by following protocol in [22] using ResNet50 features (deep methods are with ResNet50 as backbone)

2. Office-Home dataset:

3. Image-CLEF DA dataset:

Now the original supplementary:

### 1 Classification Accuracy on Office-31 Dataset

We check the performance of MEDA in another widely-used dataset: Office-31 [15]. Office-31 is a standard benchmark for domain adaptation tasks in multimedia analysis. It consists of 4,652 images and 31 categories from three domains: Amazon (A), Webcam (w), and DSLR (D). Each two domain can construct a domain adaptation task, leading to 6 tasks:  $A \rightarrow D$ ,  $A \rightarrow W$ ,  $\cdots$ ,  $W \rightarrow D$ . We follow the protocol in [22] and evaluate all the methods in these tasks.

Table 4 shows the classification of MEDA and other state-of-the-art traditional and deep domain adaptation methods. Note that MEDA and other traditional methods used the DeCaf7 features, while deep methods used the original

<sup>\*</sup>The oroginal paper can be found at https://arxiv.org/abs/1807.07258. Contact: wangjindong@ict.ac.cn

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Method	$Ar \to Cl$	$\mathrm{Ar}  ightarrow \mathrm{Pr}$	$Ar \to Rw$	$\text{Cl} \to \text{Ar}$	$\text{Cl} \to \text{Pr}$	$\text{Cl} \to \text{Rw}$	$\text{Pr} \rightarrow \text{Ar}$	$\text{Pr} \rightarrow \text{Cl}$	$\mathrm{Pr}  ightarrow \mathrm{Rw}$	$Rw \rightarrow Ar$	$Rw \to Cl$	$Rw \to Pr$	Avg
AlexNet	26.4	32.6	41.3	22.1	41.7	42.1	20.5	20.3	51.1	31.0	27.9	54.9	34.3
DAN [9]	31.7	43.2	55.1	33.8	48.6	50.8	30.1	35.1	57.7	44.6	39.3	63.7	44.5
DANN [5]	36.4	45.2	54.7	35.2	51.8	55.1	31.6	39.7	59.3	45.7	46.4	65.9	47.3
JAN [12]	35.5	46.1	57.7	36.4	53.3	54.5	33.4	40.3	60.1	45.9	47.4	67.9	48.2
CDAN-RM [10]	36.2	47.3	58.6	37.3	54.4	58.3	33.2	43.9	62.1	48.2	48.1	70.7	49.9
CDAN-M [10]	38.1	50.3	60.3	39.7	56.4	57.8	35.5	43.1	63.2	48.4	48.5	71.1	51.0
ResNet-50	34.9	50.0	58.0	37.4	41.9	46.2	38.5	31.2	60.4	53.9	41.2	59.9	46.1
DAN [9]	43.6	57.0	67.9	45.8	56.5	60.4	44.0	43.6	67.7	63.1	51.5	74.3	56.3
DANN [5]	45.6	59.3	70.1	47.0	58.5	60.9	46.1	43.7	68.5	63.2	51.8	76.8	57.6
JAN [12]	45.9	61.2	68.9	50.4	59.7	61.0	45.8	43.4	70.3	63.9	52.4	76.8	58.3
CDAN-RM [10]	49.2	64.8	72.9	53.8	62.4	62.9	49.8	48.8	71.5	65.8	56.4	79.2	61.5
CDAN-M [10]	50.6	65.9	73.4	55.7	62.7	64.2	51.8	49.1	74.5	68.2	56.9	80.7	62.8
MEDA	54.6	75.2	77.0	56.5	72.8	72.3	59.0	51.9	78.2	67.7	57.2	81.8	67.0

Table 2: Classification accuracy (%) on Office-Home dataset using ResNet50 features (deep methods are with ResNet50 as backbone)

Table 3: Classification accuracy (%) on Image-CLEF DA dataset using ResNet-50 as features(deep methods are with ResNet50 as backbone)

Method	$I \rightarrow P$	$P \rightarrow I$	$I \rightarrow C$	$C \rightarrow I$	$\mathbf{C}  ightarrow \mathbf{P}$	$P \rightarrow C$	Avg
AlexNet	66.2	70.0	84.3	71.3	59.3	84.5	73.9
DAN [9]	67.3	80.5	87.7	76.0	61.6	88.4	76.9
DANN [5]	66.5	81.8	89.0	79.8	63.5	88.7	78.2
JAN [12]	67.2	82.8	91.3	80.0	63.5	91.0	79.3
CDAN-RM [10]	67.0	84.8	92.4	81.3	64.7	91.6	80.3
CDAN-M [10]	67.7	83.3	91.8	81.5	63.0	91.5	79.8
ResNet-50	74.8	83.9	91.5	78.0	65.5	91.2	80.7
DAN [9]	74.5	82.2	92.8	86.3	69.2	89.8	82.5
DANN [5]	75.0	86.0	96.2	87.0	74.3	91.5	85.0
RTN [11]	75.6	86.8	95.3	86.9	72.7	92.2	84.9
JAN [12]	76.8	88.0	94.7	89.5	74.2	91.7	85.8
MADA [14]	75.0	87.9	96.0	88.8	75.2	92.2	85.8
CDAN-RM [10]	77.2	88.3	98.3	90.7	76.7	94.0	87.5
CDAN-M [10]	78.3	91.2	96.7	91.2	77.2	93.7	88.1
CAN [21]	78.2	87.5	94.2	89.5	75.8	89.2	85.7
iCAN [21]	79.5	89.7	94.7	89.9	78.5	92.0	87.4
MEDA	79.7	92.5	95.7	92.2	78.5	95.5	89.0

images. From these results, we can observe that MEDA still achieves the best classification accuracy. This indicates the effectiveness of MEDA over other methods.

#### 2 Parameter Sensitivity

In order to check the regularization parameter sensitivity of MEDA, we run MEDA with a wide range of parameter values for  $\lambda$ ,  $\eta$ , and  $\rho$  on several selected tasks. Then we compare its performance with the best baseline method. The results are in Figure 1. Those results indicate that MEDA can achieve a **robust** performance with regard to a wide range of parameter values.

Specifically, the best choices of those parameters are:  $\lambda \in [0.5, 1000], \eta \in [0.01, 1]$ , and  $\rho \in [0.01, 5]$ . To sum up, the performance of MEDA stays robust with a large range of regularization parameter choice. Therefore, the parameters do not need to be fine-tuned in practical applications.

*Remark*: Although MEDA is easy to use, and its parameters do not have to be fine-tuned, in addition, for research purpose, we also interpret how to further tune those parameters. We choose parameters according to following rules: 1st, SRM on source domain is very important, so we tend to choose a small  $\eta$  to make sure MEDA does not degenerate. 2nd, distribution adaptation is inevitable in SRM, so we choose a slightly larger  $\lambda$  to make it count. 3rd, we choose  $\rho$  by following [1]. 4th, p is set following [2].

ie with Alexiver as	<i>backbone</i> )						
Method	$A \rightarrow D$	$A \rightarrow W$	$D \rightarrow A$	$\mathrm{D} \to \mathrm{W}$	$W \rightarrow A$	$W \to D$	Average
SVM	55.7	50.6	46.5	93.1	43.0	97.4	64.4
TCA [13]	45.4	40.5	36.5	78.2	34.1	84.0	53.1
GFK [7]	52.0	48.2	41.8	86.5	38.6	87.5	59.1
SA [4]	46.2	42.5	39.3	78.9	36.3	80.6	54.0
DANN [6]	34.0	34.1	20.1	62.0	21.2	64.4	39.3
CORAL [17]	57.1	53.1	51.1	94.6	47.3	98.2	66.9
AlexNet [8]	63.8	61.6	51.1	95.4	49.8	99.0	70.1
DDC [20]	64.4	61.8	52.1	95.0	52.2	98.5	70.6
DAN [9]	67.0	68.5	54.0	96.0	53.1	99.0	72.9
RTN [11]	71.0	73.3	50.5	96.8	51.0	99.6	73.7
DCORAL [18]	66.4	66.8	52.8	95.7	51.5	99.2	72.1
DUCDA [22]	68.3	68.3	53.6	96.2	51.6	99.7	73.0
MEDA	69.5	69.9	58.0	94.0	56.0	96.8	74.0

Table 4: Classification accuracy (%) on Office-31 dataset by following protocol in [22] using DeCaf6 features (deep methods are with AlexNet as backbone)



Figure 1: Parameter sensitivity on selected tasks: (a)  $\lambda$ , (b)  $\eta$ , (c)  $\rho$ .

#### **3** Detailed Results of the Estimation of Adaptive Factor $\mu$

The evaluation of the adaptive factor  $\mu$  is important for the dynamic distribution adaptation. Other than the results in the main paper (Section 4.5.2), we list all the results of our estimation of  $\mu$  in both Table 5 and Table 6. The results clearly demonstrated the effectiveness of our solution in quantitatively estimating the adaptive factor.

Although most of the  $\hat{\mu}$  were close to  $\mu_{opt}$ , we also noticed that there was relatively larger gap between  $\hat{\mu}$  and  $\mu_{opt}$  on two tasks (i.e.  $C \rightarrow D$  and  $U \rightarrow M$ ). It is interesting to observe that the estimations on their opposite (i.e.  $D \rightarrow C$  and  $M \rightarrow U$  if we change the source and target) were satisfactory. We think this is probably because of the high variance of the target domain. We will continue to explore more properties of this phenomenon and improve the estimation.

Feature	Task	$\mathbf{C} \to \mathbf{A}$	$\mathbf{C} \to \mathbf{W}$	$\mathbf{C} \rightarrow \mathbf{D}$	$\mathbf{A} \rightarrow \mathbf{C}$	$\mathbf{A} \to \mathbf{W}$	$\mathbf{A} \rightarrow \mathbf{D}$	W  ightarrow C	$W \rightarrow A$	$W \rightarrow D$	$\mathbf{D} \rightarrow \mathbf{C}$	$\mathbf{D} \rightarrow \mathbf{A}$	$\mathbf{D}  ightarrow \mathbf{W}$	Avg
	$\mu_{opt}$	56.9	55.3	58.6	45.0	53.2	47.8	34.2	43.0	89.2	35.8	41.5	87.8	54.0
SURF	μ̂	56.5	53.9	50.3	43.9	53.2	45.9	34.0	42.7	88.5	34.9	41.2	87.5	52.7
	Performance Variation	-0.7%	-2.5%	-14.2%	-2.4%	0.0%	-4.0%	-0.6%	-0.7%	-0.8%	-2.5%	-0.7%	-0.3%	-2.4%
	$\mu_{opt}$	93.4	95.6	91.7	87.4	88.1	91.7	88.0	93.2	99.4	87.6	93.2	98.0	91.2
DeCaf	$\hat{\mu}$	93.4	95.6	91.1	87.4	88.1	88.1	93.2	99.4	99.4	87.5	93.2	97.6	92.8
	Performance Variation	0.0%	0.0%	-0.7%	0.0%	0.0%	-3.9%	+5.9%	<b>+6.7</b> %	0.0%	-0.1%	0.0%	-0.4%	+1.8%

Table 5: Comparison between  $\mu_{opt}$  and  $\hat{\mu}$  on Office+Caltech10 datasets using both SURF and DeCaf features

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	Task	$U \to M$	$M \to U$	$V \rightarrow I$	$\mathrm{I} \to \mathrm{V}$	AVG
	$\mu_{opt}$	76.8	89.4	81.2	67.6	78.8
	$\hat{\mu}$	72.1	89.5	74.4	67.3	75.8
	Performance Variation	-7.20%	+0.14%	-0.58%	-1.33%	-3.8%

Table 6: Comparison between  $\mu_{ont}$  and  $\hat{\mu}$  on USPS+MNIST and ImageNet+VOC2007 datasets

#### **Detailed Results of Empirical Convergence Analysis** 4

We also validate the convergence of MEDA through empirical analysis. We run randomly selected tasks of Office+Caltech datasets and all tasks of USPS+MNIST / ImageNet+VOC datasets. The total iteration number is set to be T = 20. Figure 2 presents the results. From those results, we can clearly see that MEDA could reach a steady performance in only a few (T < 10) iterations.



Figure 2: Empirical convergence analysis on all datasets.

#### **Analysis of Pseudo-labeling** 5

We understand the importance of pseudo-labeling. If the base classifier is very weak, or the pseudo labels are not confident, will that affect the results?

We validate the robustness of the pseudo-labeling through experiments. We use different base classifiers: 1-NN, 3-NN, SVM-c10, SVM-c100, and Random guessing. Since different classifiers has different learning abilities and will lead to different pseudo-labeling results, we see how that will affect the final results of the MEDA method. The experimental results are in Figure 5 and Table 7.

According to these results, although different classifiers are used to generate different confidence of the pseudolabeling, our MEDA is significantly robust to the classifiers. Therefore, MEDA is very easy to use. (Even random guessing could lead to comparable performance. However, since random guessing is not a technical method, we prefer to use 1-NN)

Base classifier	Accuracy of base classifier	Accuracy of MEDA
1-NN	45.20	56.99
3-NN	45.41	55.64
SVM-c10	31.62	54.90
SVM-c100	52.30	55.84
Random	9.60	55.53

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Figure 3: Results of different base classifiers used in MEDA on  $C \rightarrow A$  task.

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